

ELEVATING EFFICIENCY

AN ELEVATOR SIMULATION

SIMULATION

CODE STRUCTURE

CALLED FROM MAIN.PY

SIMULATION

BUILDING

STATISTICS

PYGAME

LIVE-PLOTTER

CALLED
SEPARATELY

PLOTTER

SIMULATION

BUILDING

BUILDING

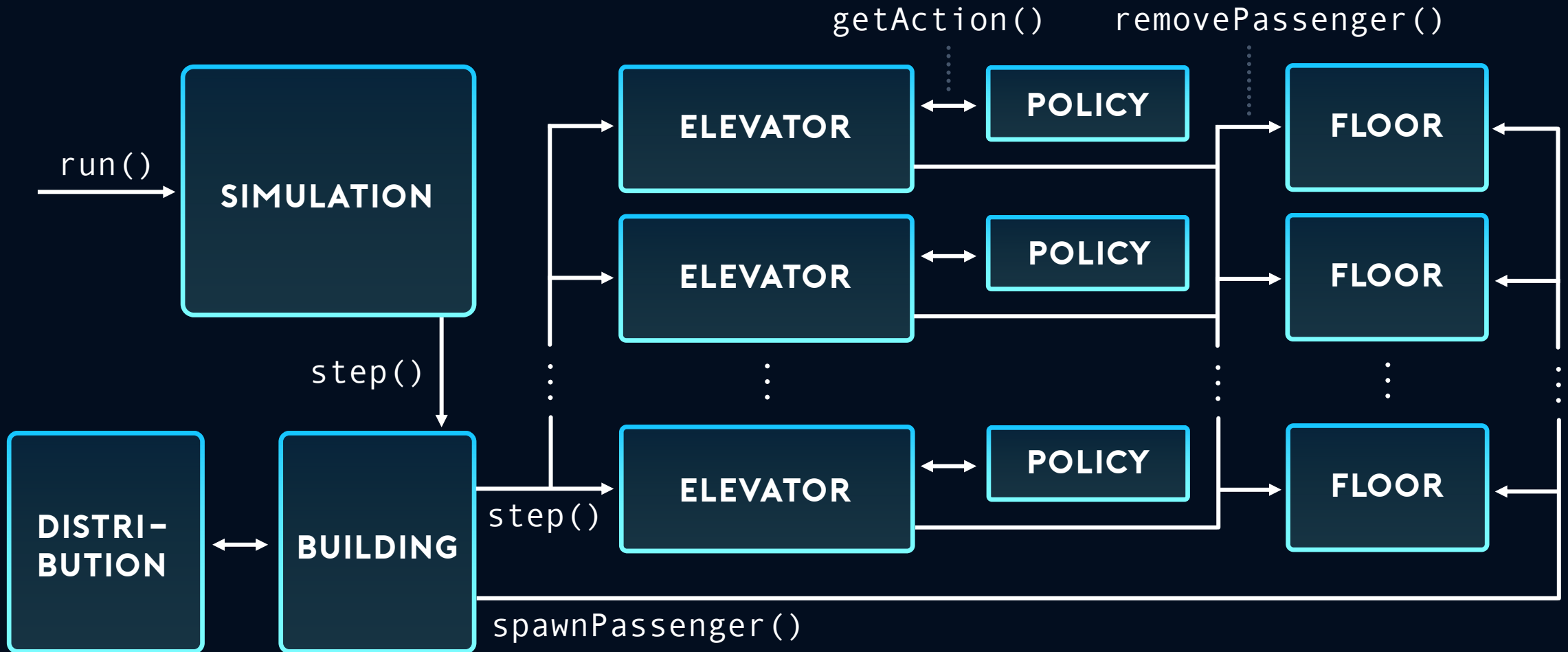
FLOORS
10 Floor Objects

ELEVATORS
Two elevators
with one
Policy each

DISTRIBUTION

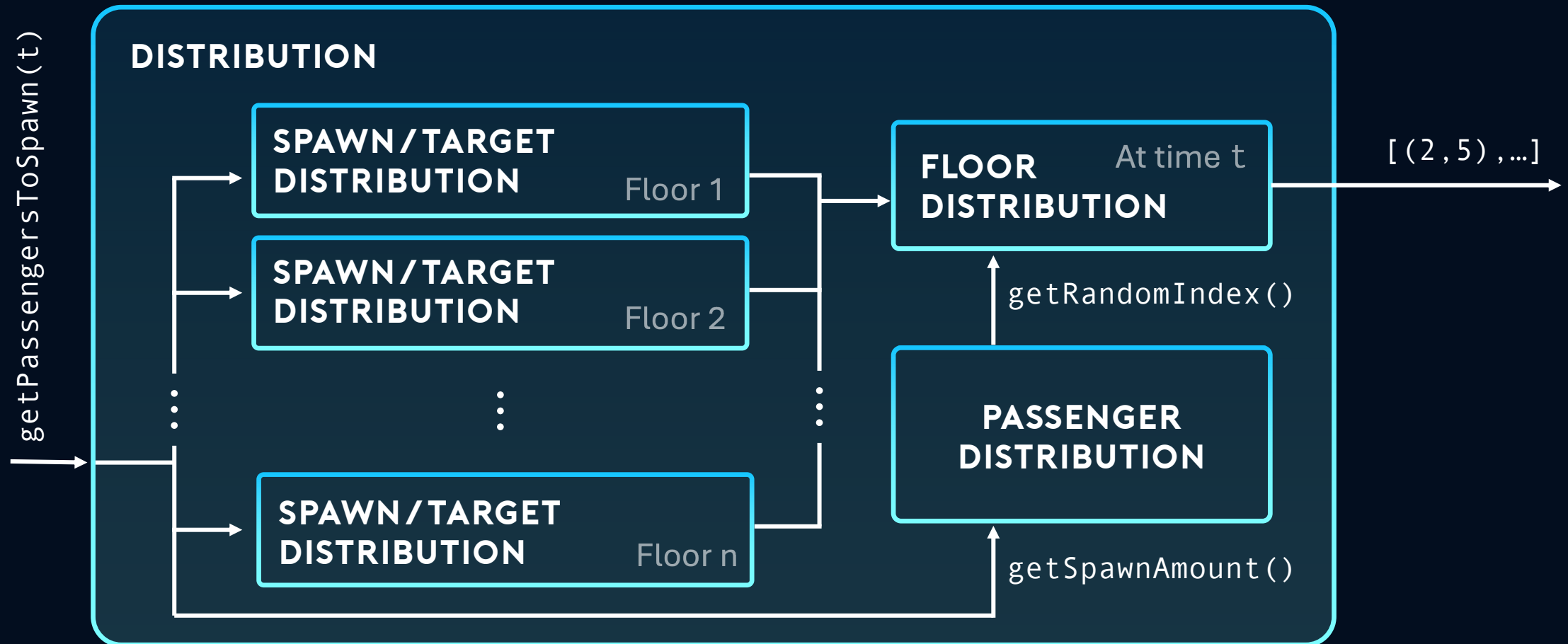
SIMULATION

EXECUTION FLOW



DISTRIBUTIONS

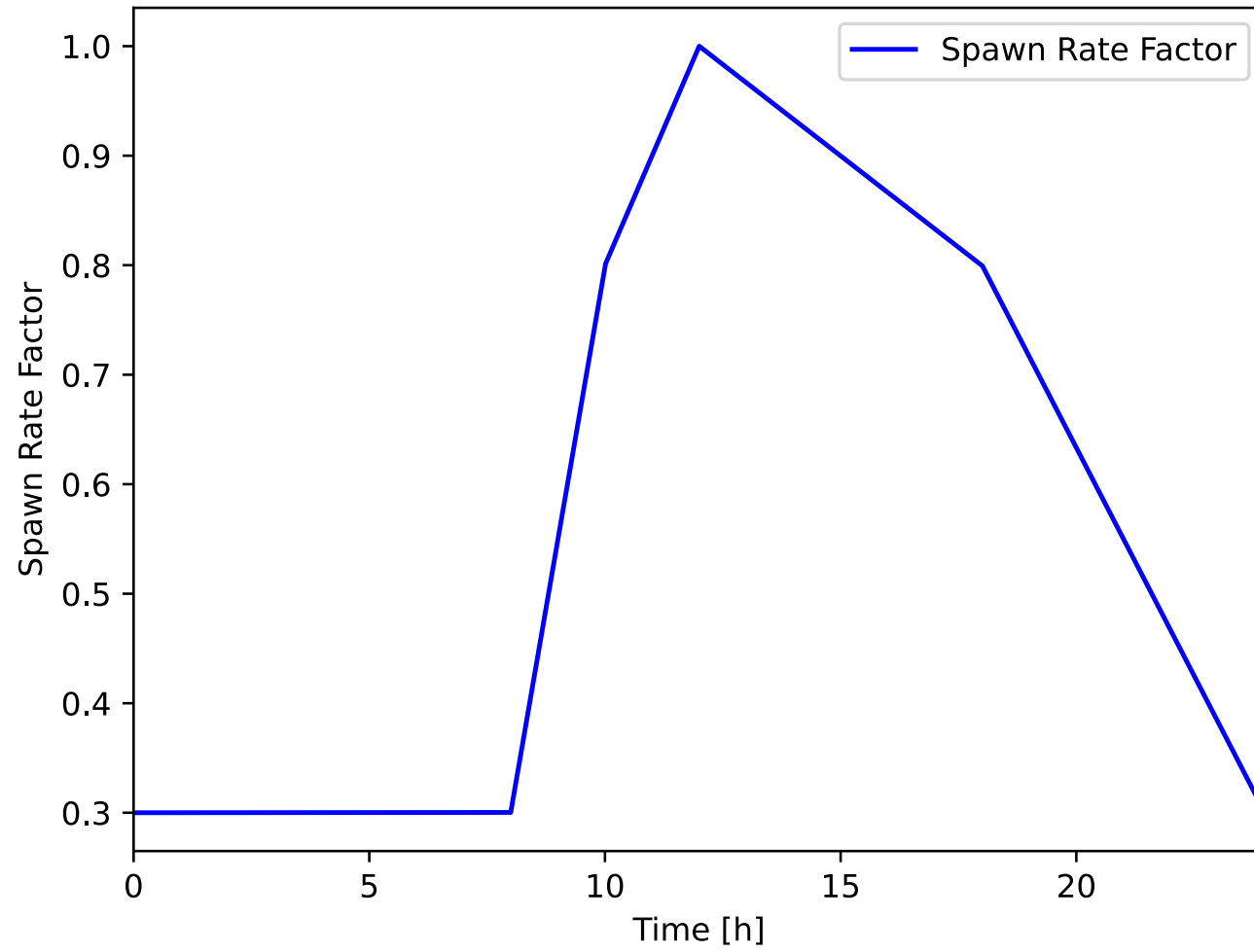
STRUCTURE



SCENARIOS

SHOPPING MALL

Shopping Mall - Passenger Distribution

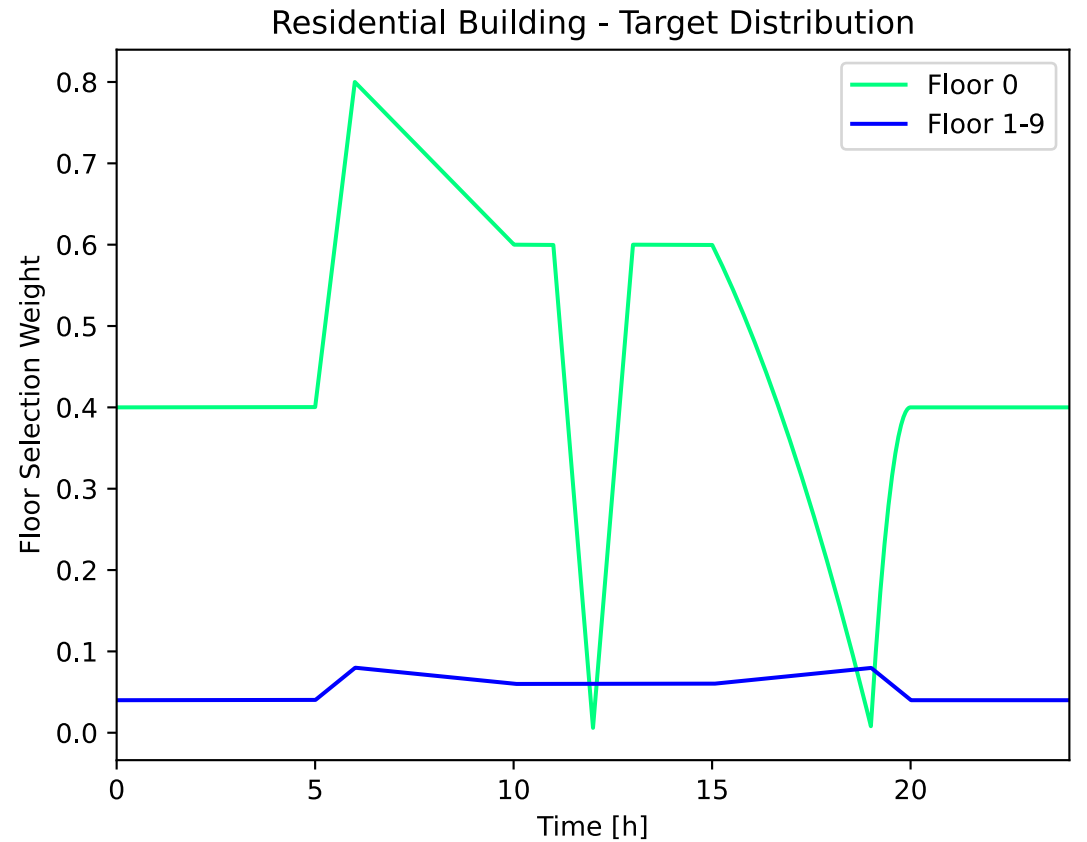
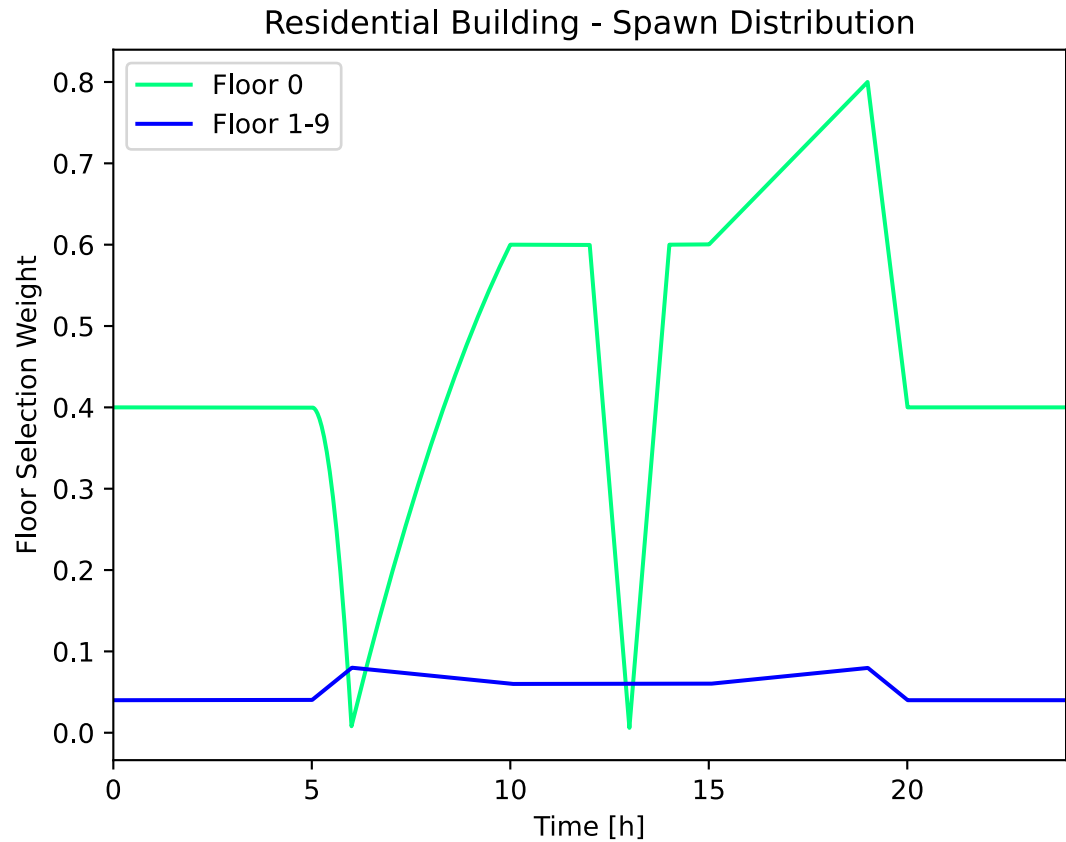


SCENARIOS

RESIDENTIAL BUILDING

SCENARIOS

RESIDENTIAL BUILDING



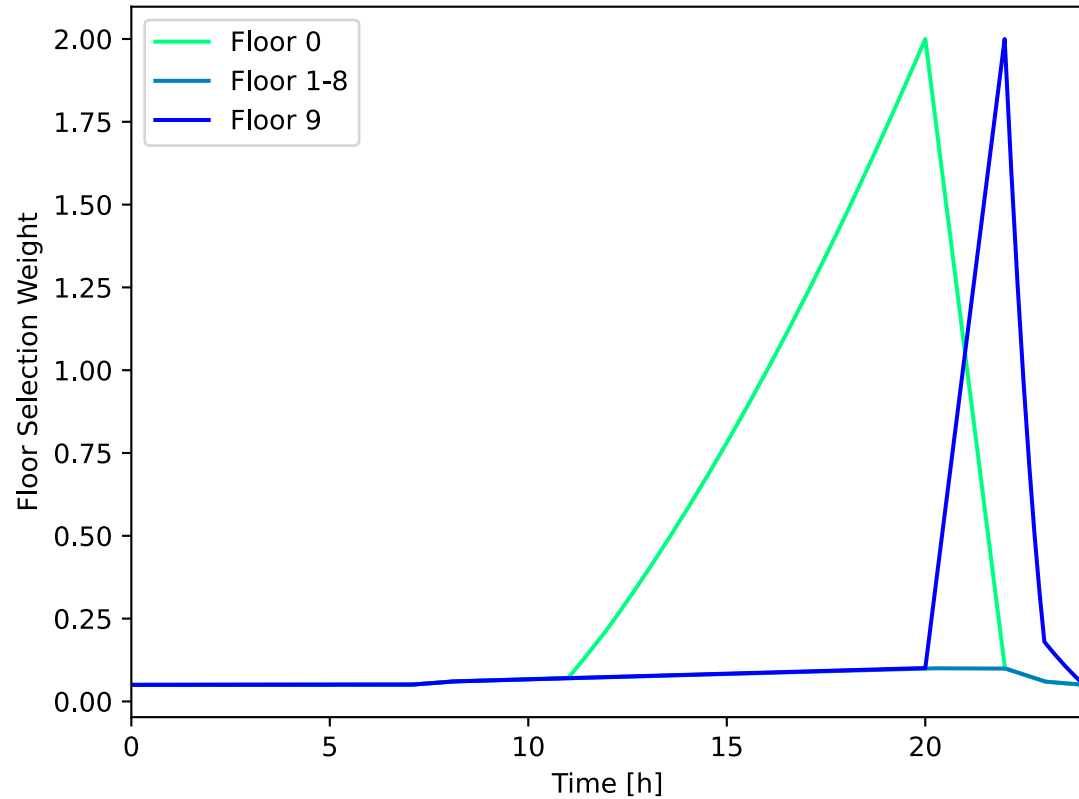
SCENARIOS

ROOFTOP BAR

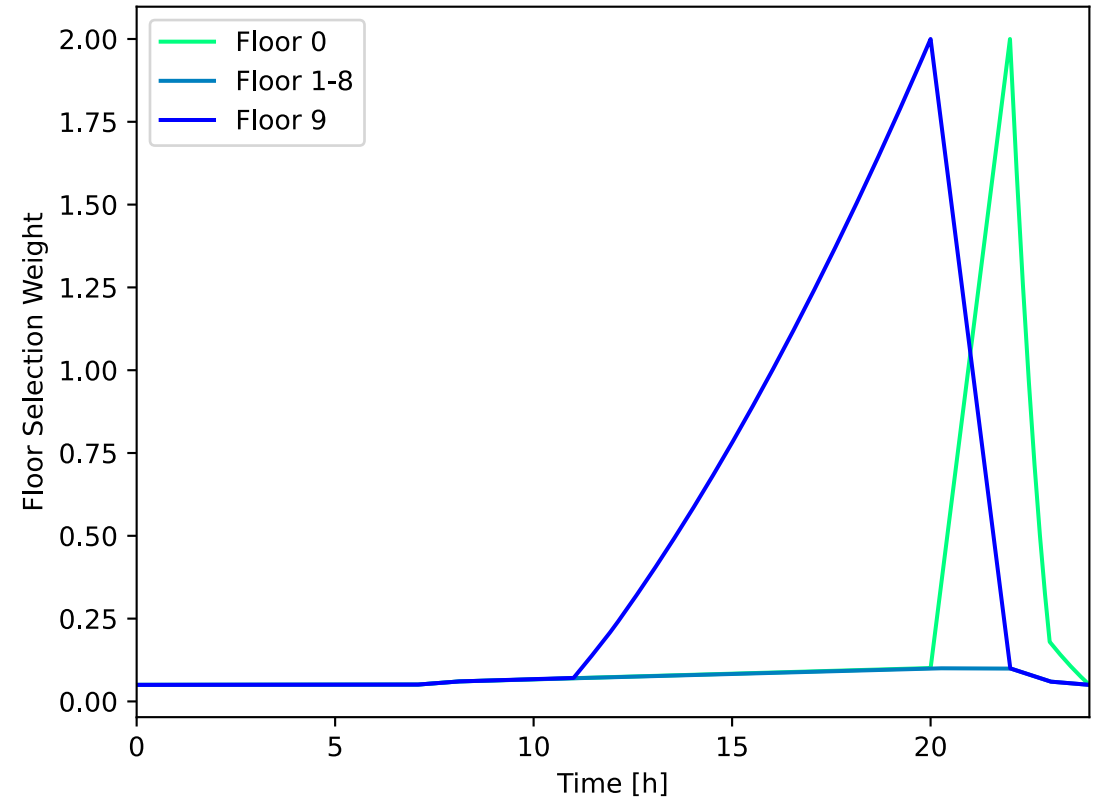
SCENARIOS

ROOFTOP BAR

Rooftop Bar - Spawn Distribution



Rooftop Bar - Target Distribution



POLICIES

POLICIES

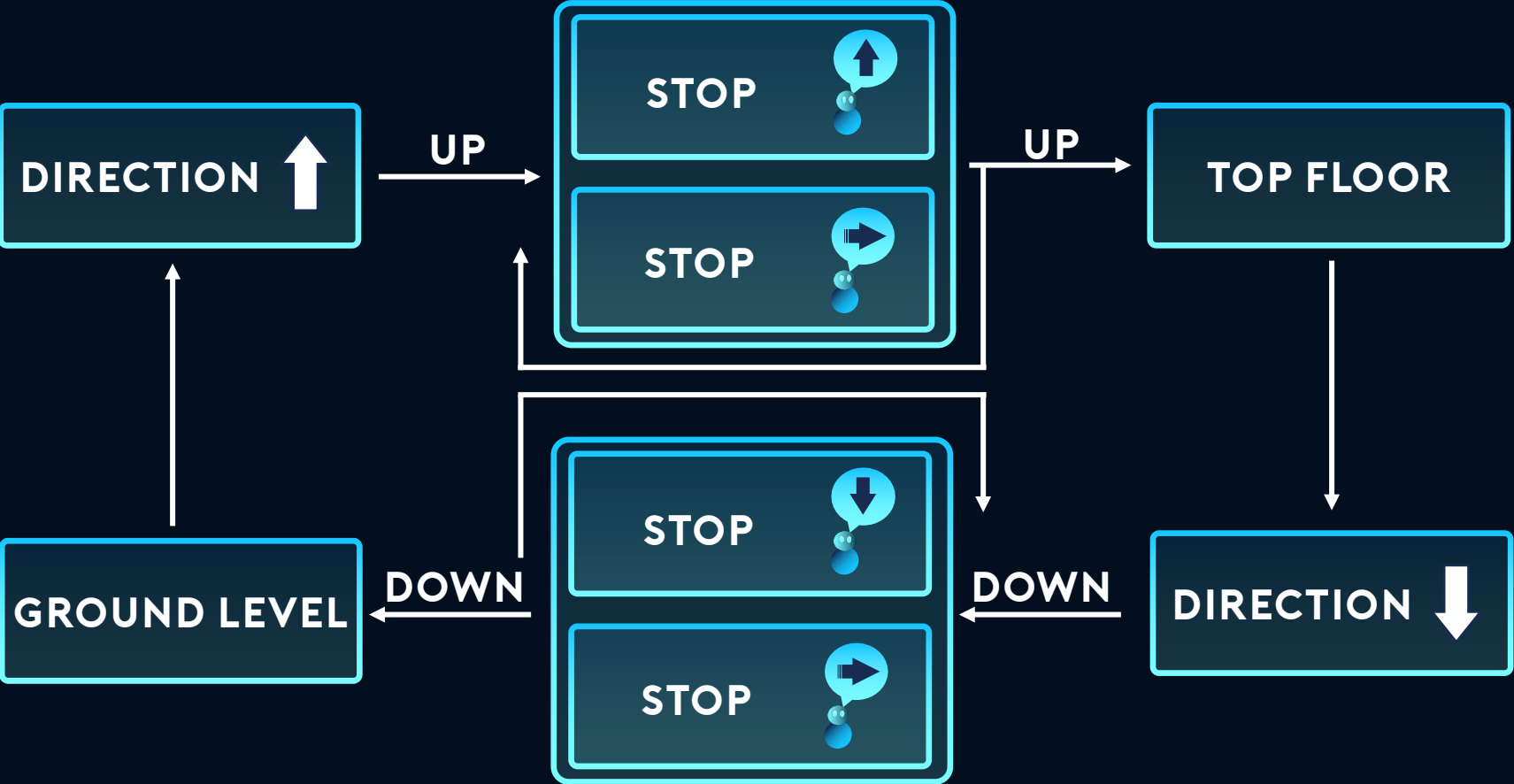
AVERAGE WAITING TIME

[...] ‘passenger-centric’ parameters are becoming more widely used. The most popular of those are waiting time (sometimes used on its own) or waiting time and travelling time (with equal weighting or with extra weighting to the waiting element). These provide a much better representation of the performance of these modern systems [...]

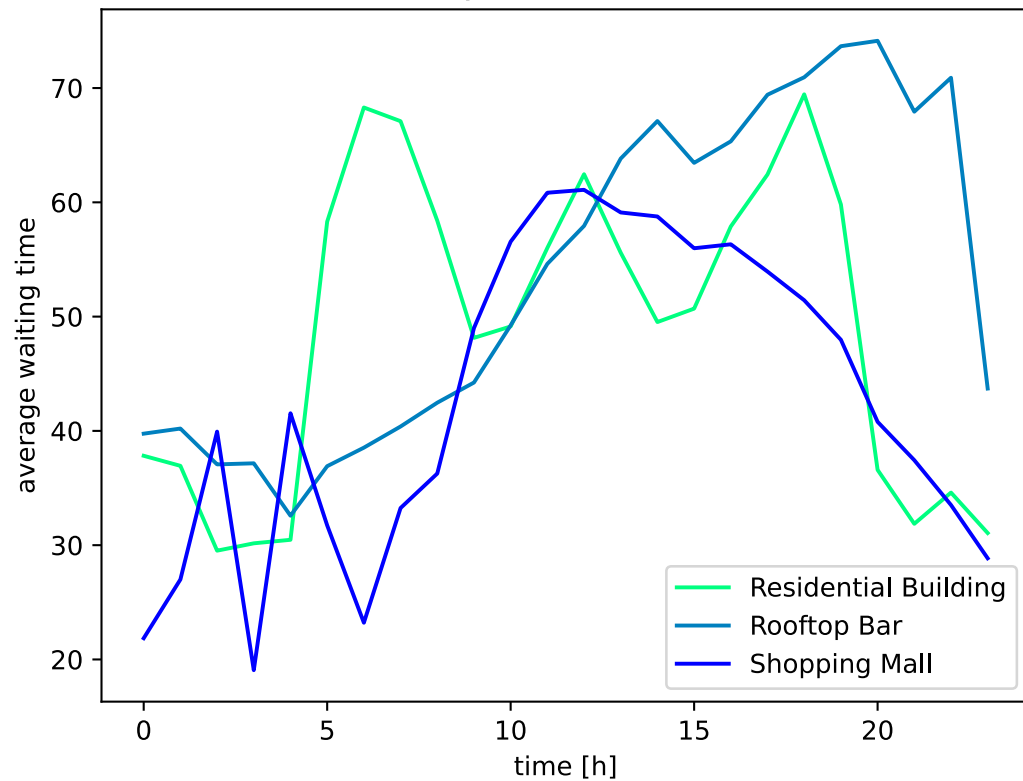
Lutfi Al-Sharif, (2015) The Average Waiting Time and the Average Travelling Time (METE VII), pp. 15

POLICIES

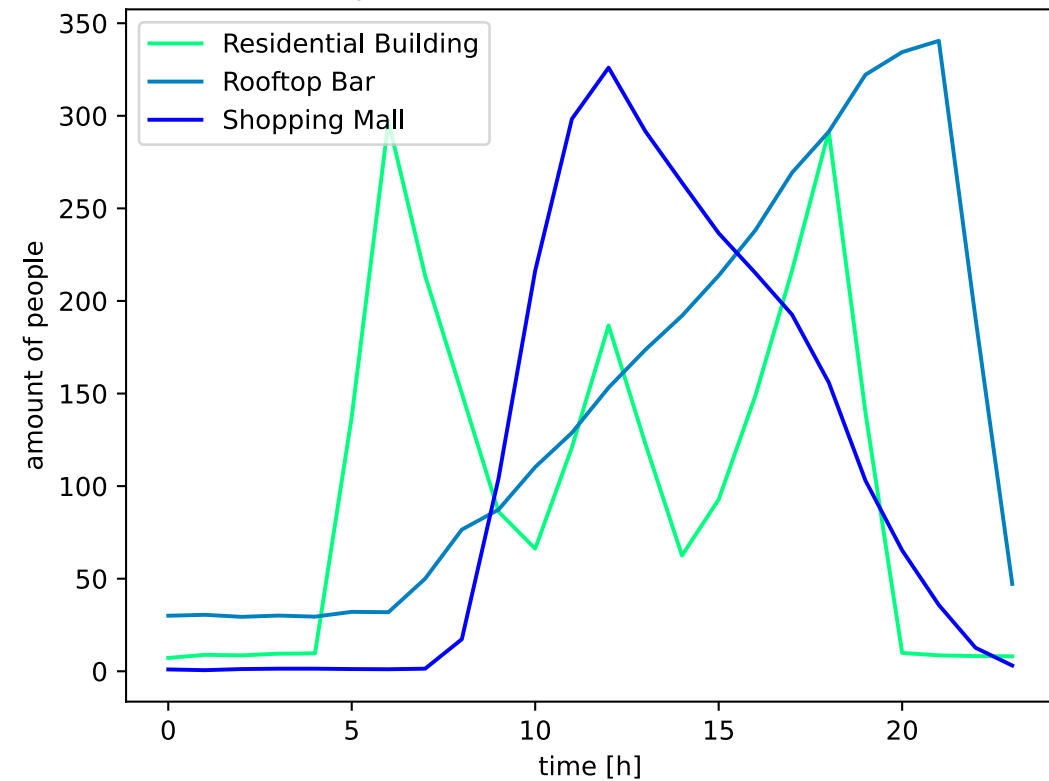
SCAN POLICY



SCANPolicy in different Scenarios



Spawnrate in different Scenarios

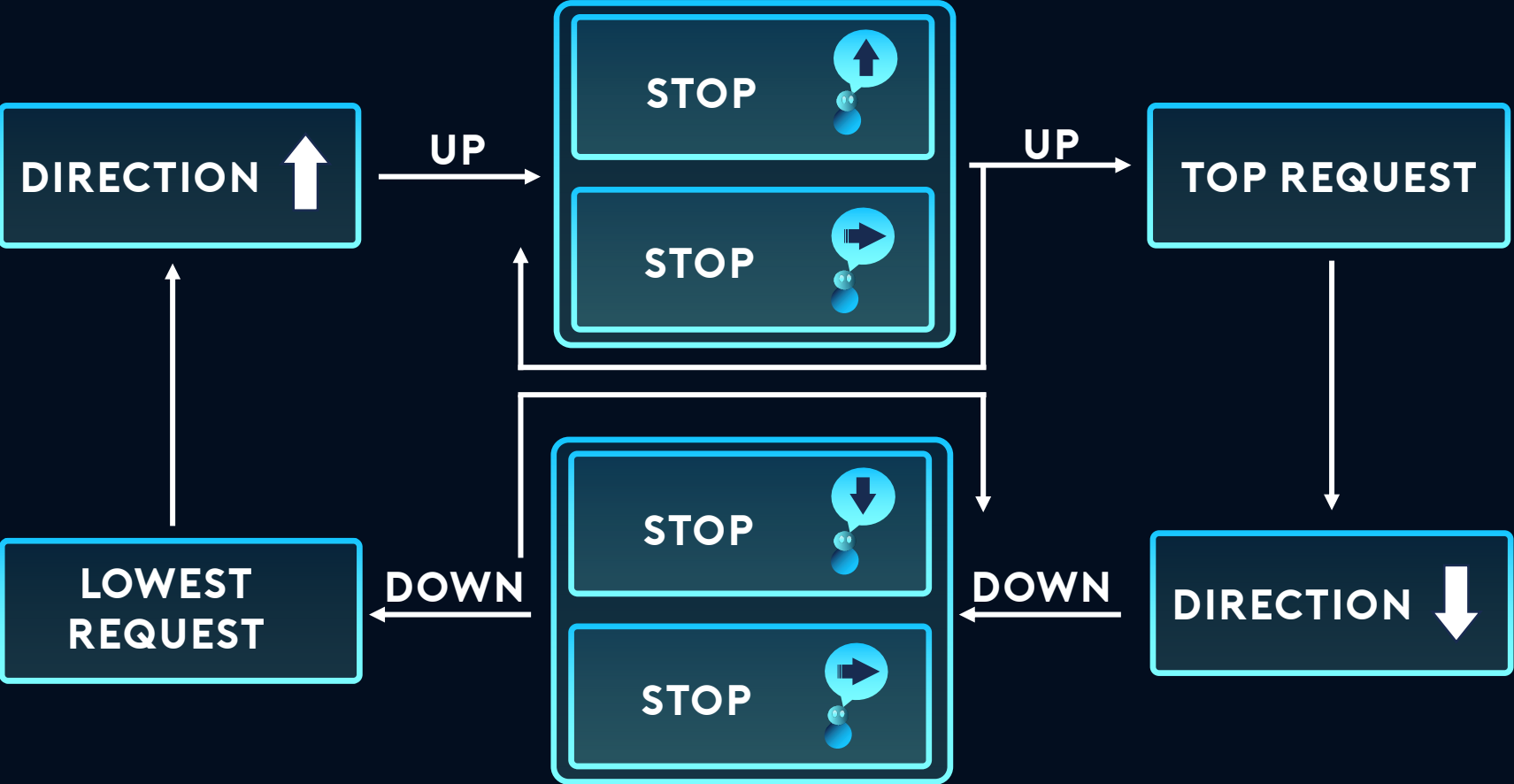


LIVE DEMO

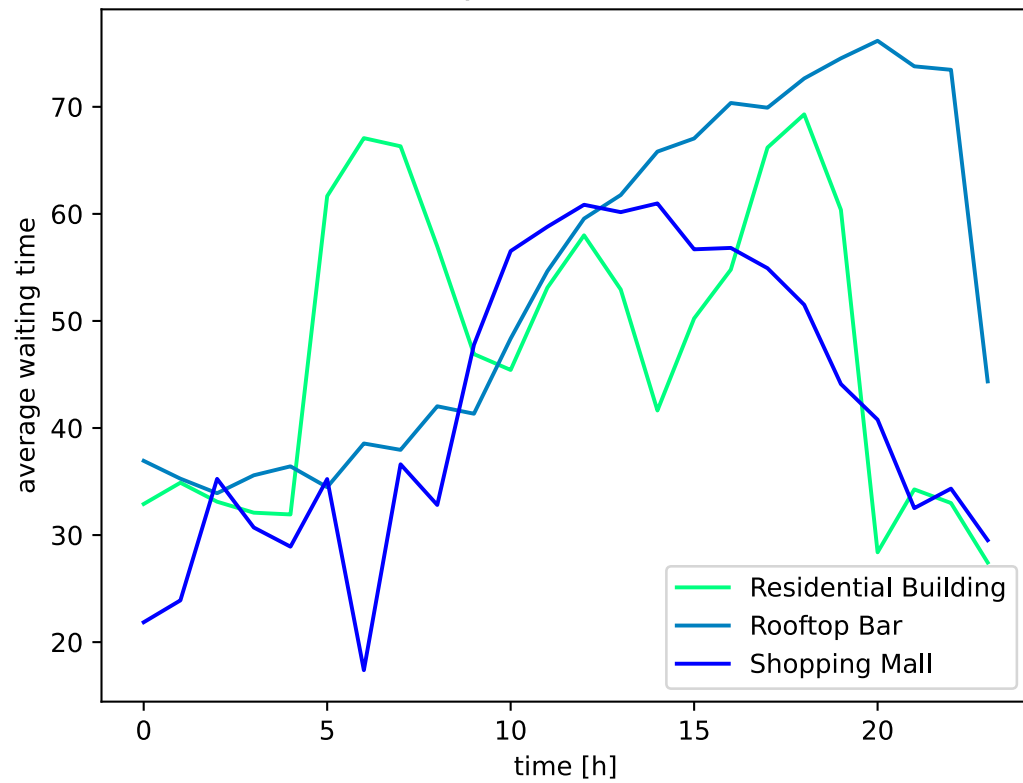
SCAN POLICY

POLICIES

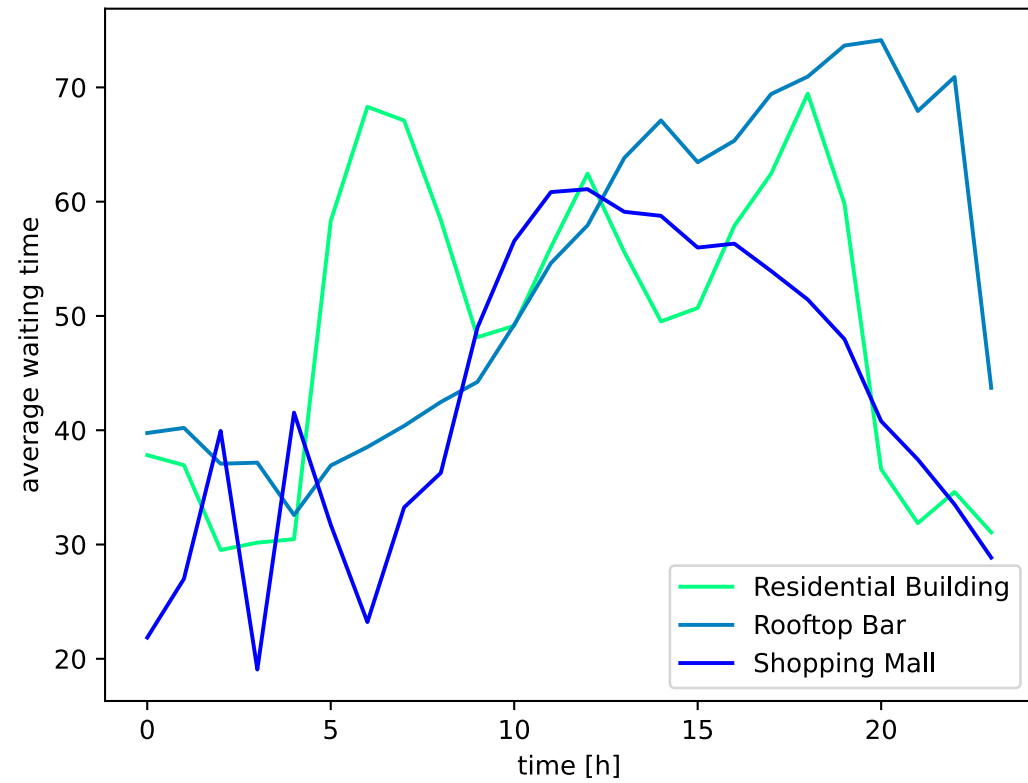
LOOK POLICY



LOOKPolicy in different Scenarios

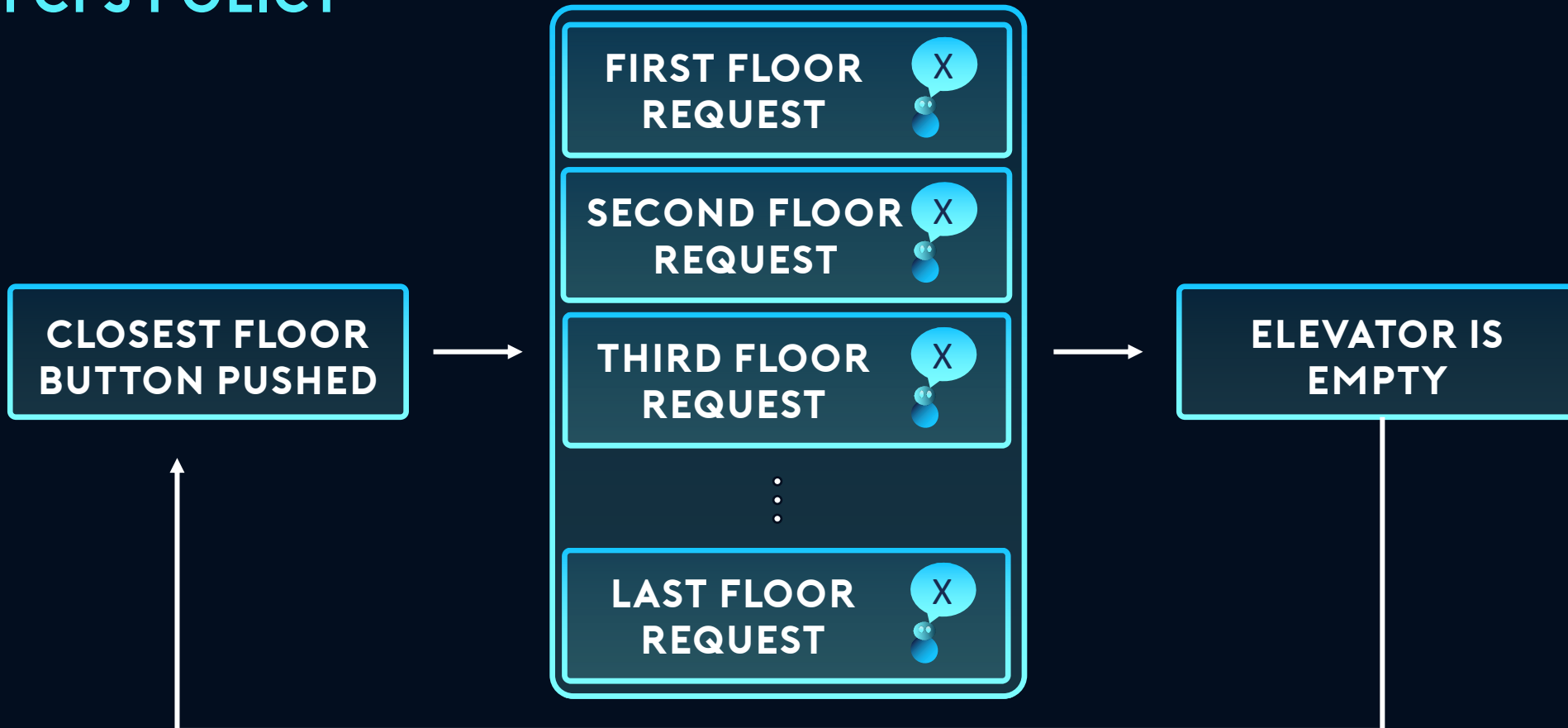


SCANPolicy in different Scenarios

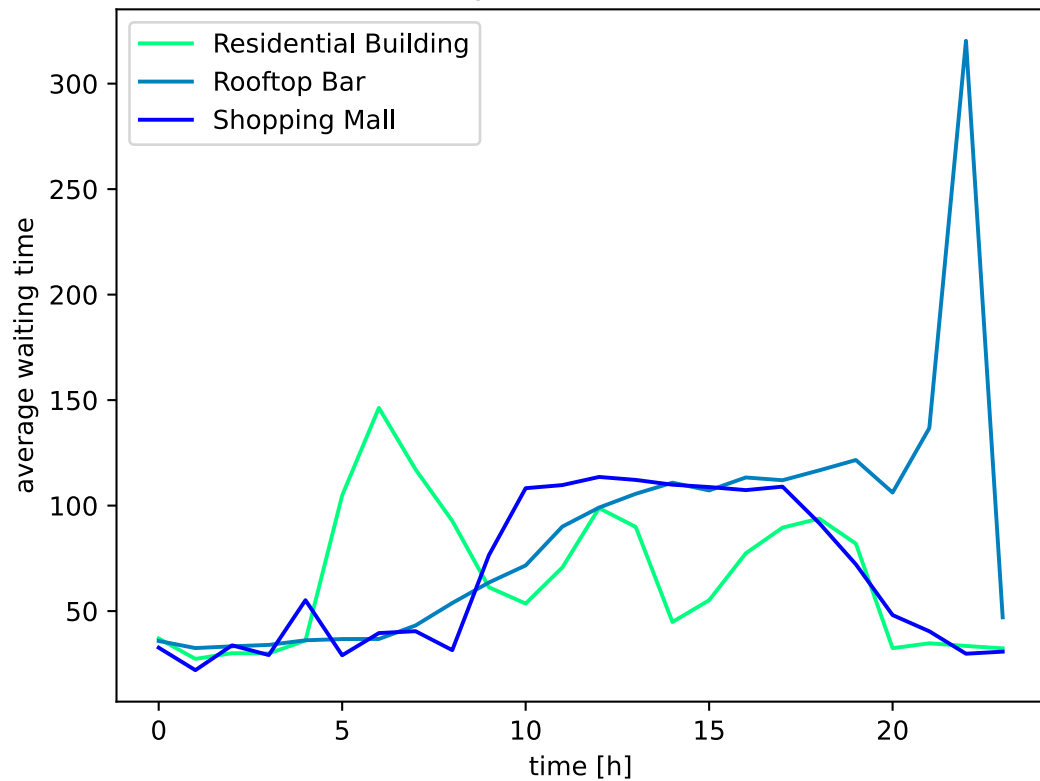


POLICIES

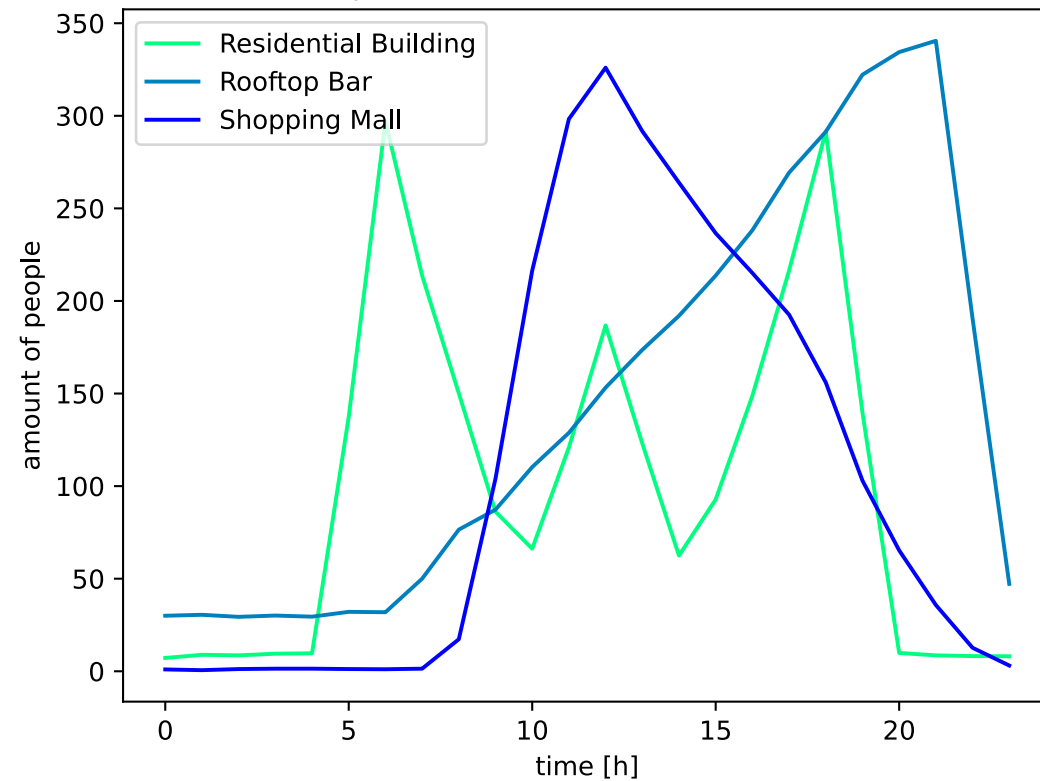
FCFS POLICY



FCFSPolicy in different Scenarios



Spawnrate in different Scenarios

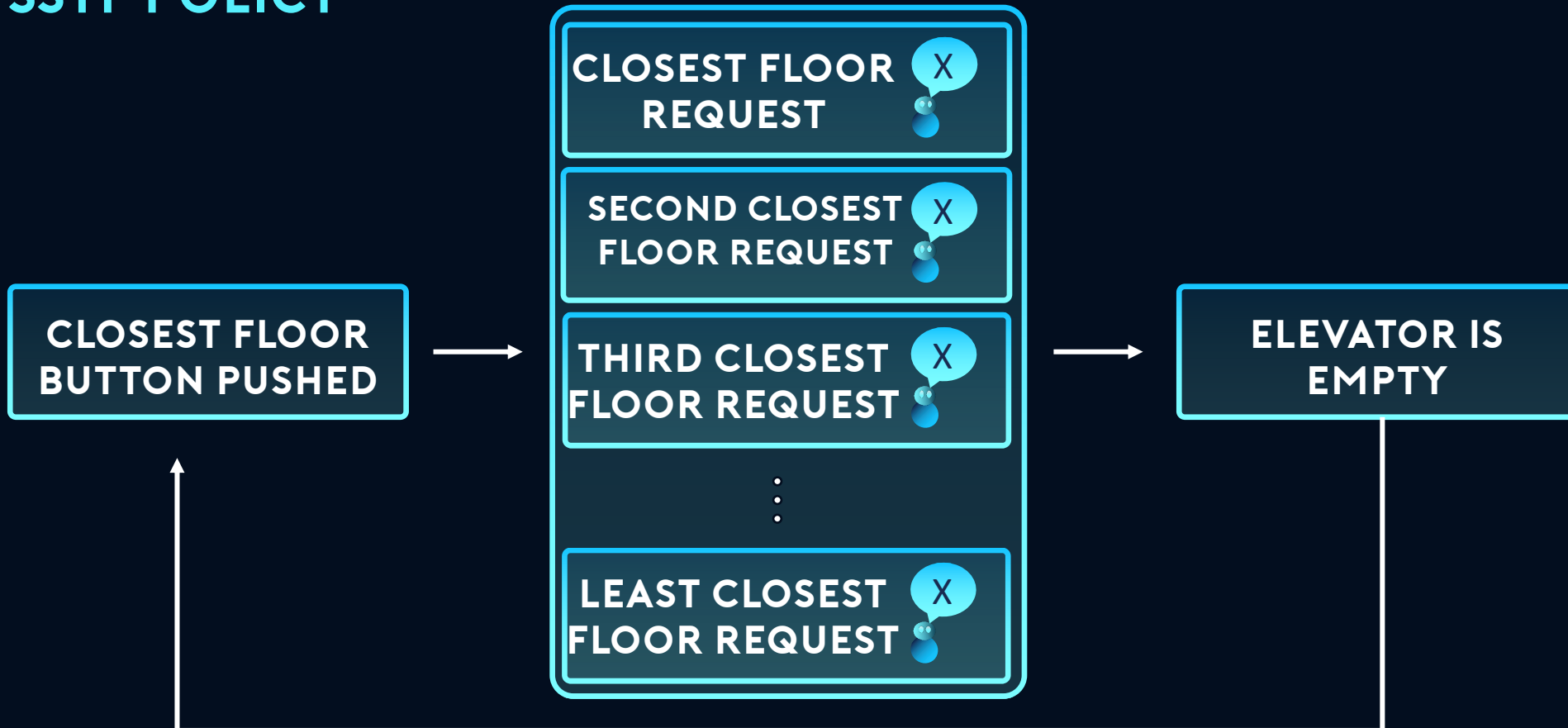


LIVE DEMO

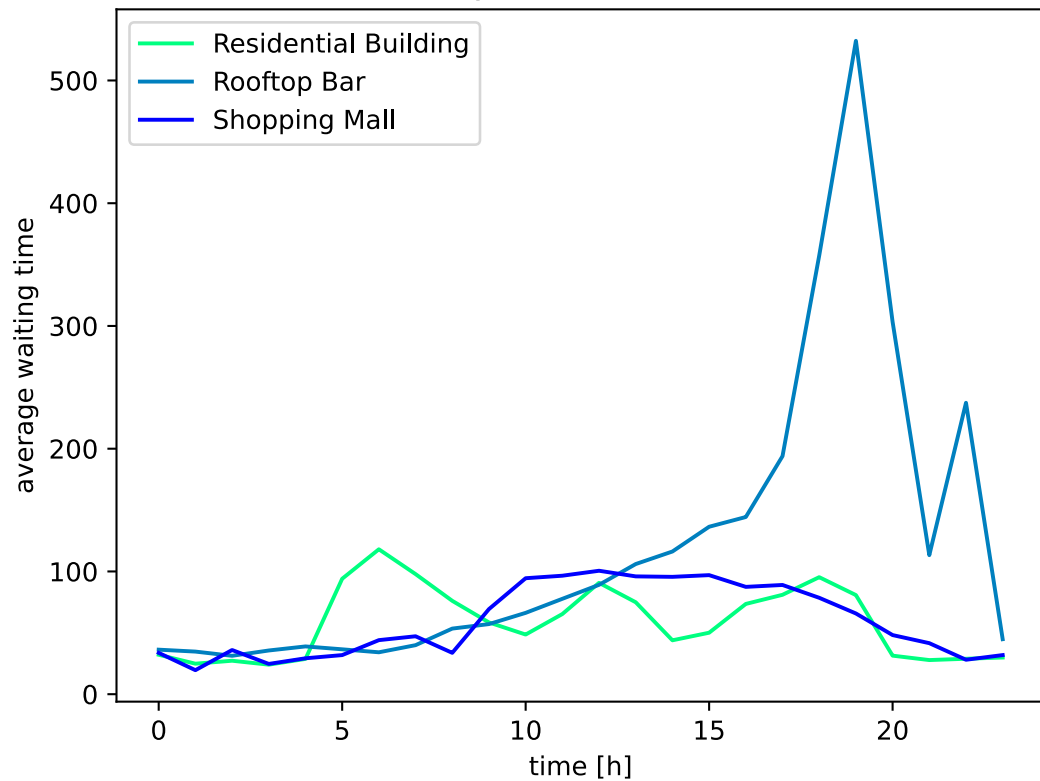
FCFS POLICY

POLICIES

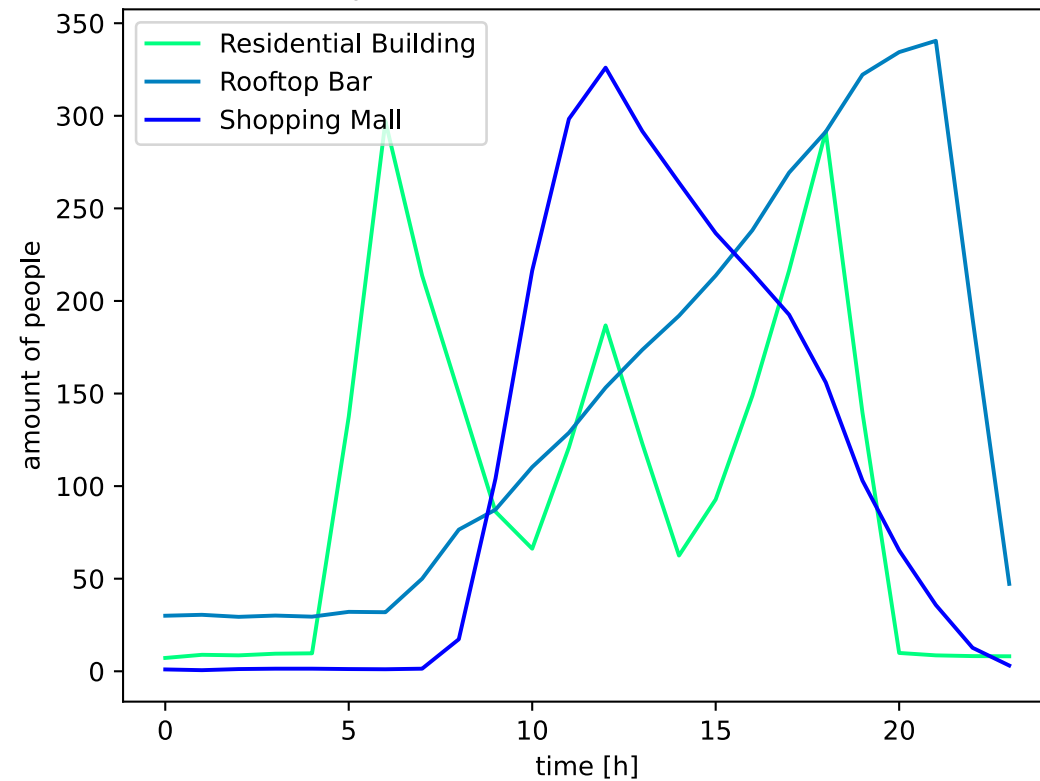
SSTF POLICY



SSTFPolicy in different Scenarios



Spawnrate in different Scenarios



SPONTANEOUS ALIGNMENT

A GENERAL PROBLEM

LIVE DEMO

SPONTANEOUS ALIGNMENT

PWDP POLICY

PARAMETRIZED POLICY

PWDP POLICY

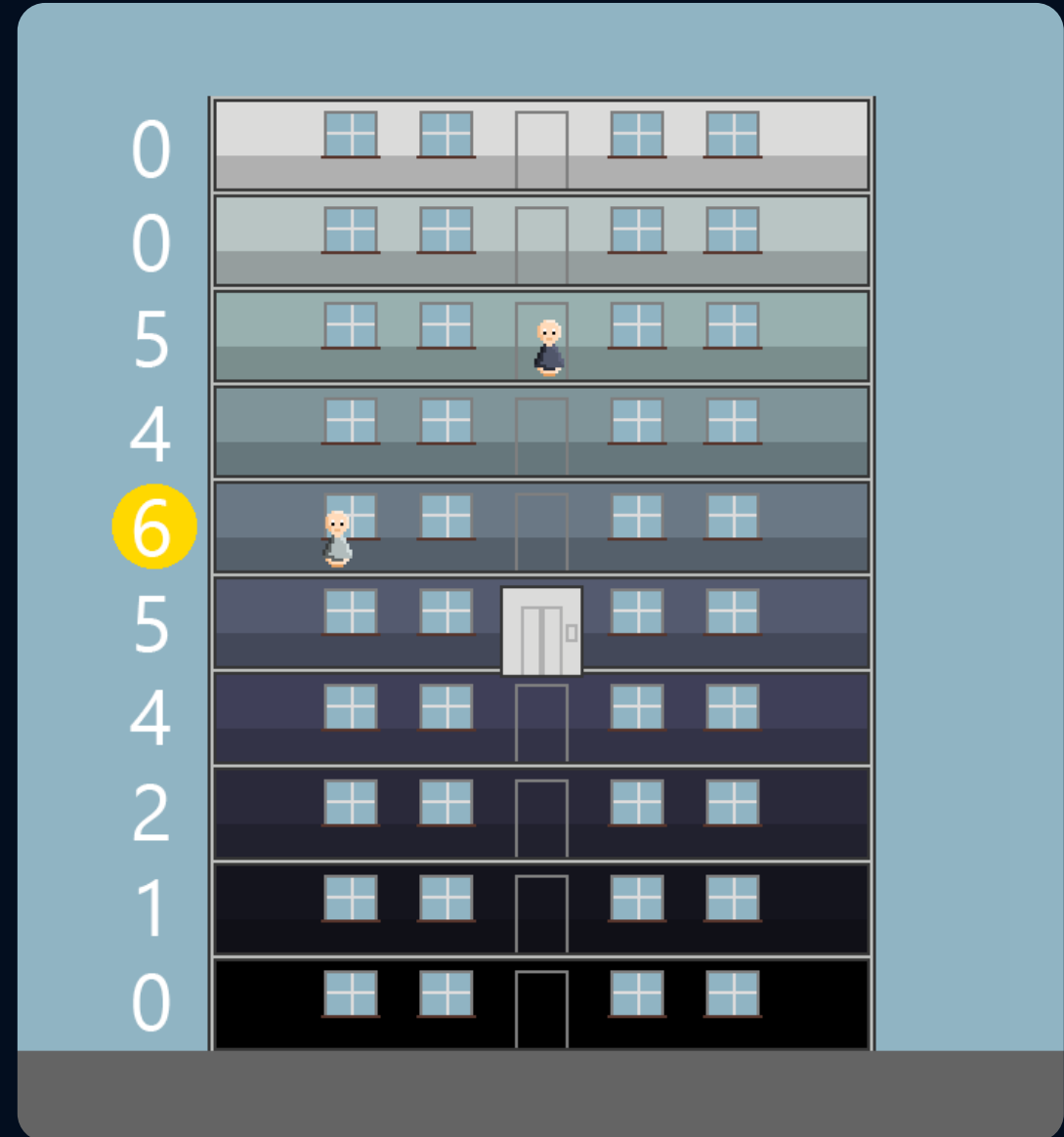
PARAMETERIZED WEIGHTED DECISION POLICY

- Our own attempt of a policy
- Tackles flaws of other policies
- Weighted decisions

PWDP POLICY

SCORE

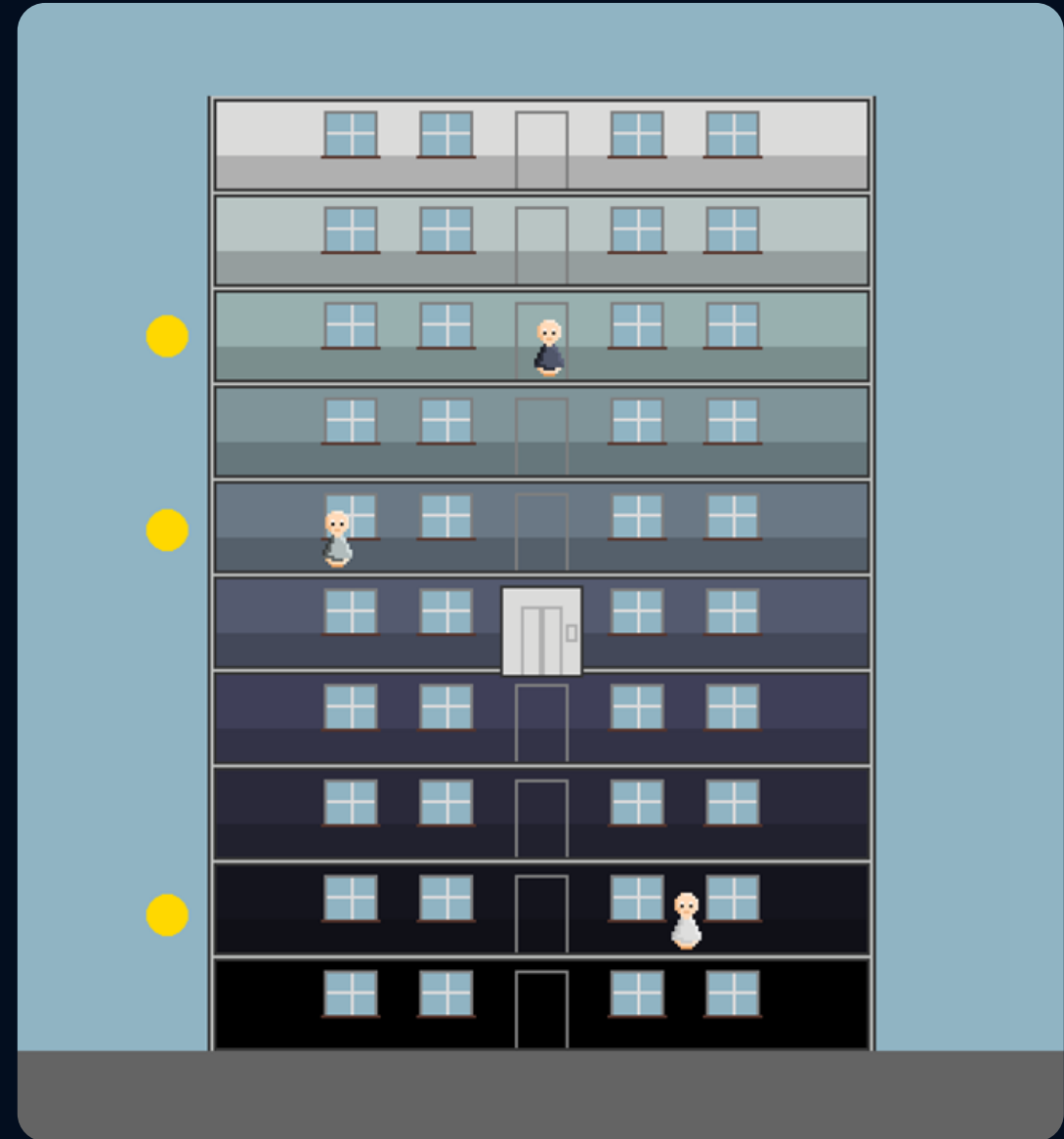
$$\text{Score}[i] = \frac{s_1 + s_2 + s_3 + s_4}{\max\{1, s_5 + s_6\}}$$



PARAMETERS

FLOOR BUTTON WEIGHT

$$s_1 = \text{flButton}W \cdot \text{flButtonPressed}[i]$$



PARAMETERS

FLOOR TIME WEIGHT

$$s_2 = \text{flButtonW} \cdot \text{flButtonTimeW} \cdot$$

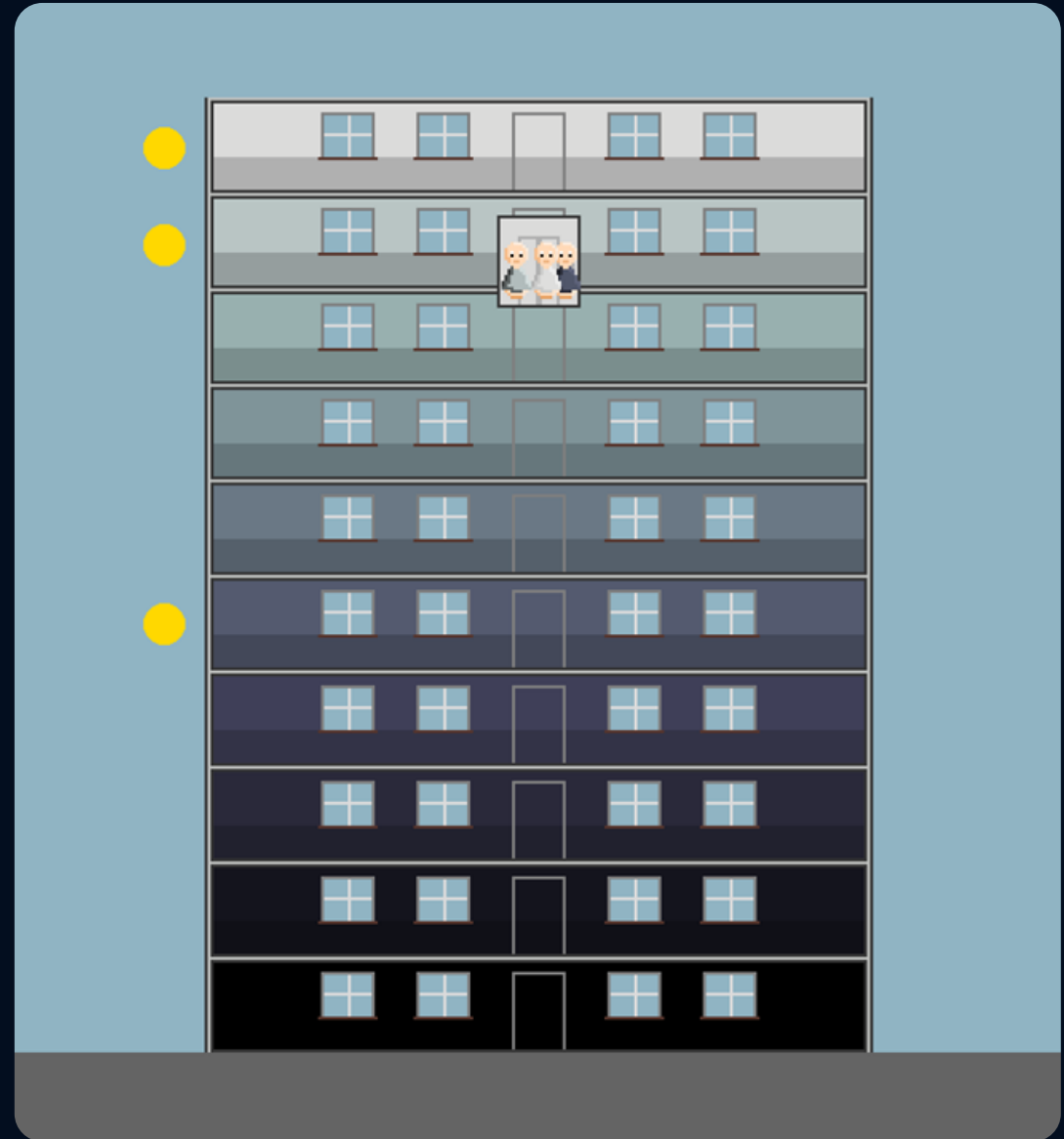
$$\text{flButtonPressed}[i] \cdot \frac{\text{flButtonTime}[i]}{\max\{1, \max\text{FlButtonTime}\}}$$



PARAMETERS

ELEVATOR BUTTON WEIGHT

$$s_3 = \text{elButtonW} \cdot \text{elButtonPressed}[i]$$

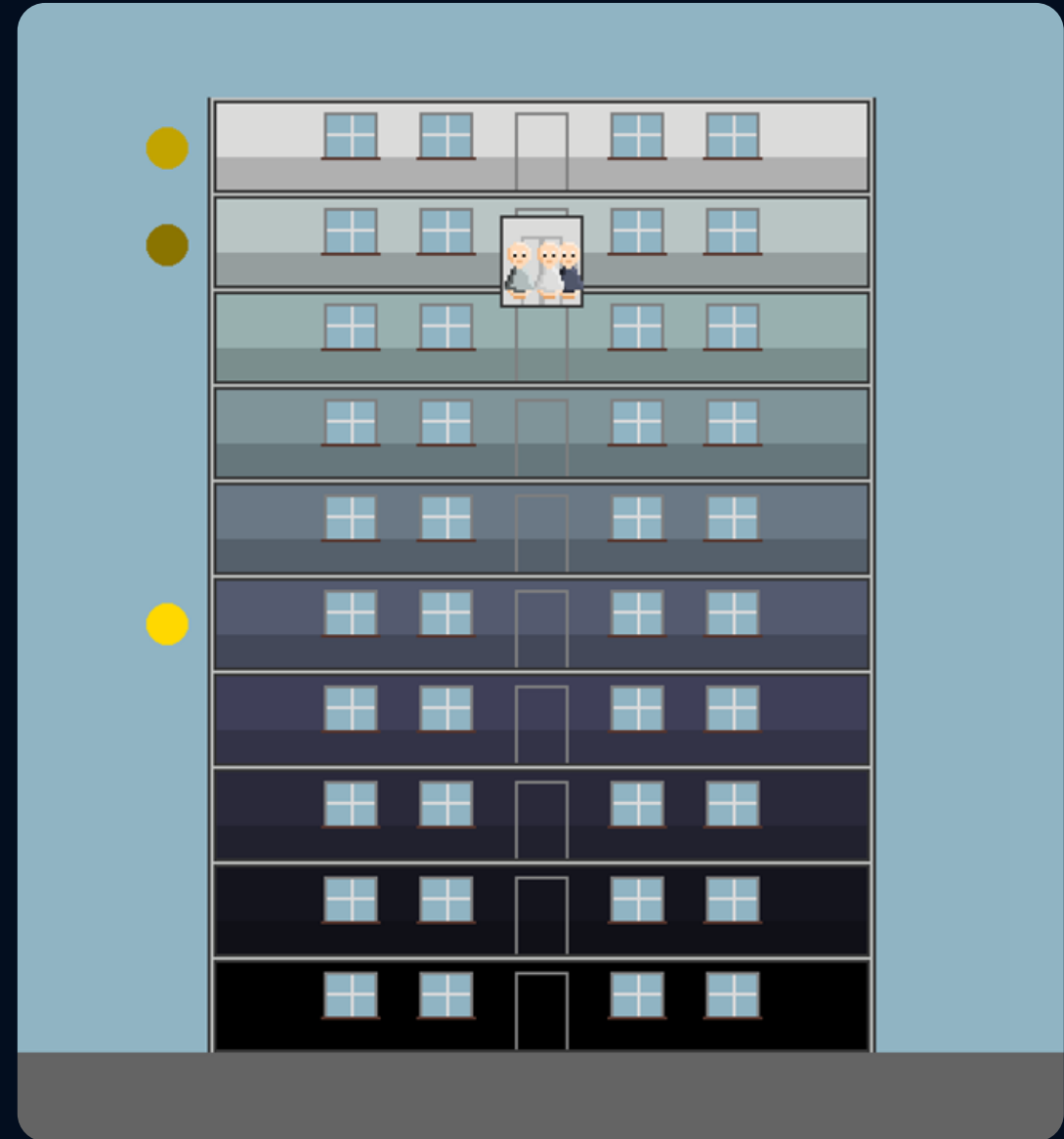


PARAMETERS

ELEVATOR TIME WEIGHT

$$s_4 = \text{elButtonW} \cdot \text{elButtonTimeW} \cdot$$

$$\text{elButtonPressed}[i] \cdot \frac{\text{elButtonTime}[i]}{\max\{1, \max\text{ElButtonTime}\}}$$

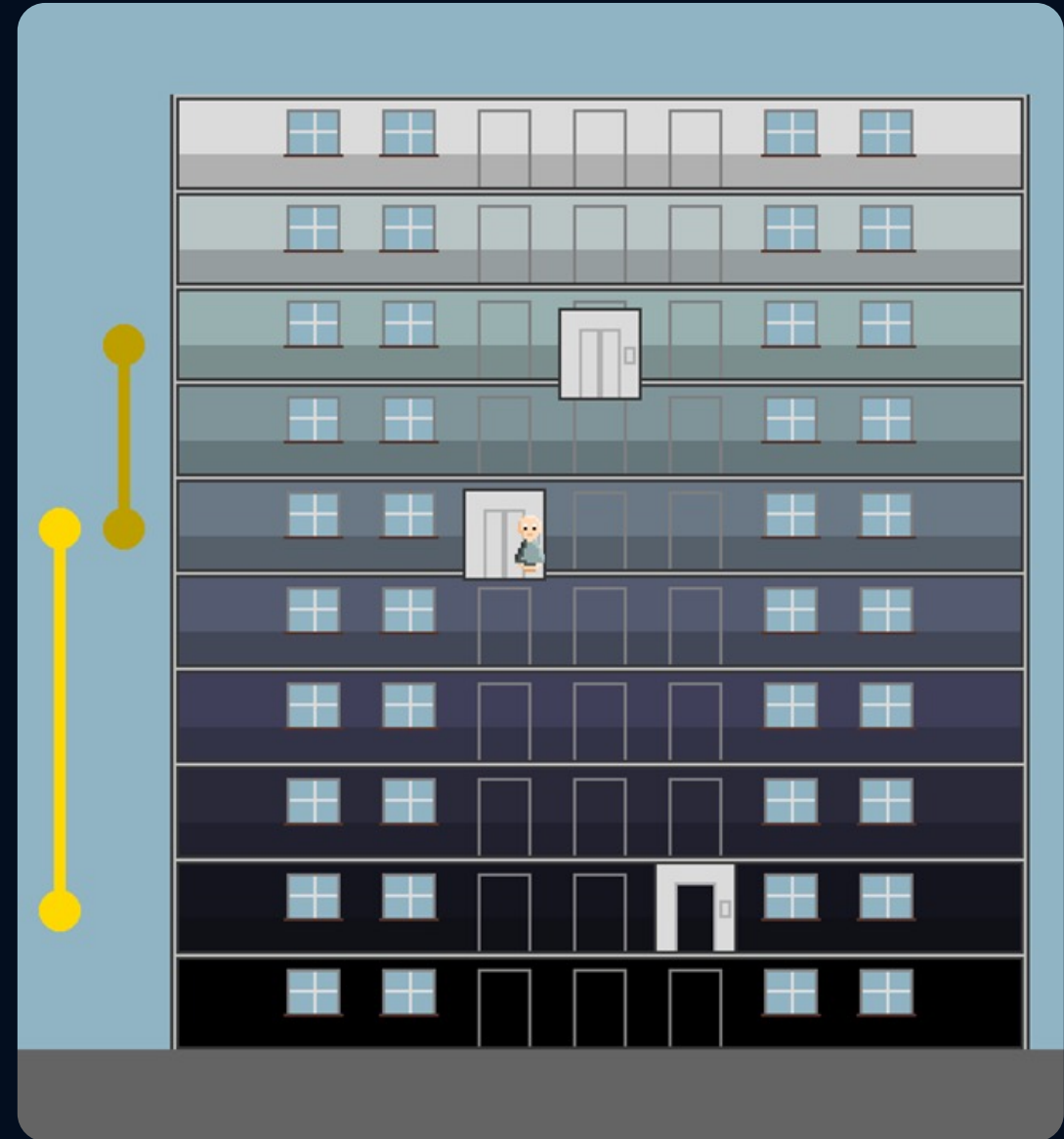


PARAMETERS

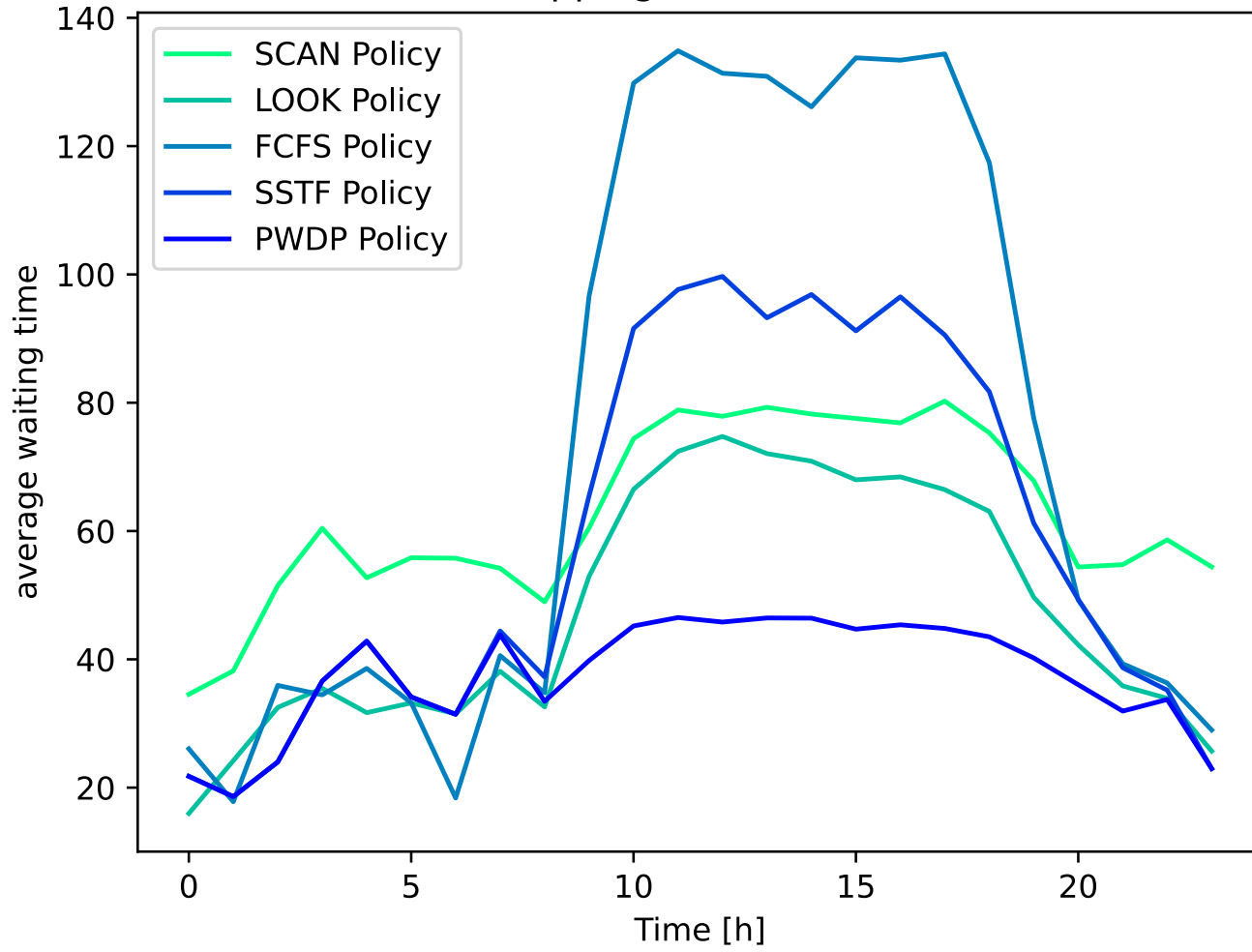
COMPETITOR WEIGHT

$s_5 = \text{competitorW}$.

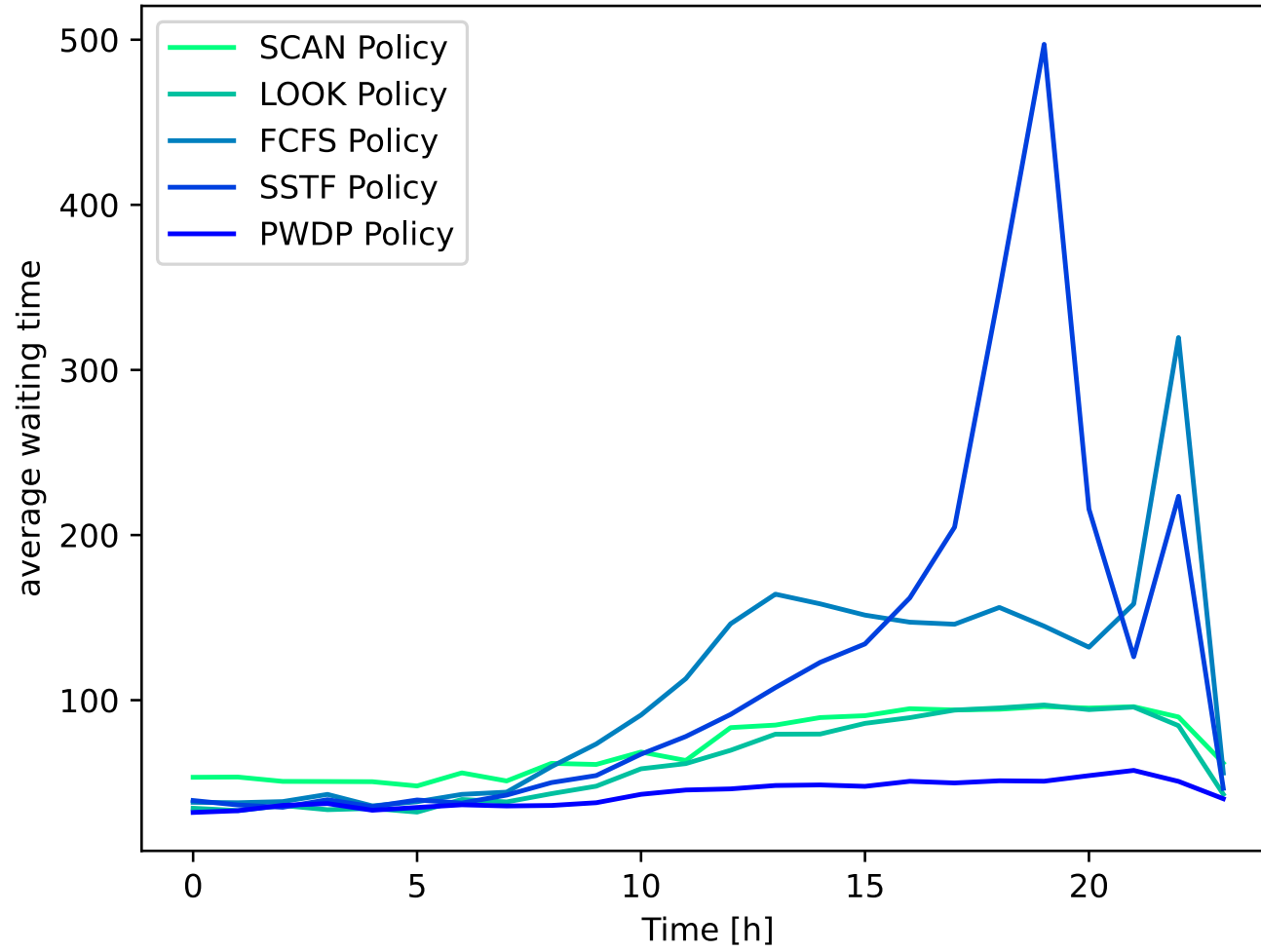
$$\sum_{j \neq \text{elIndex}} \text{distToOtherElevator}[j]$$



Shopping Mall Scenario

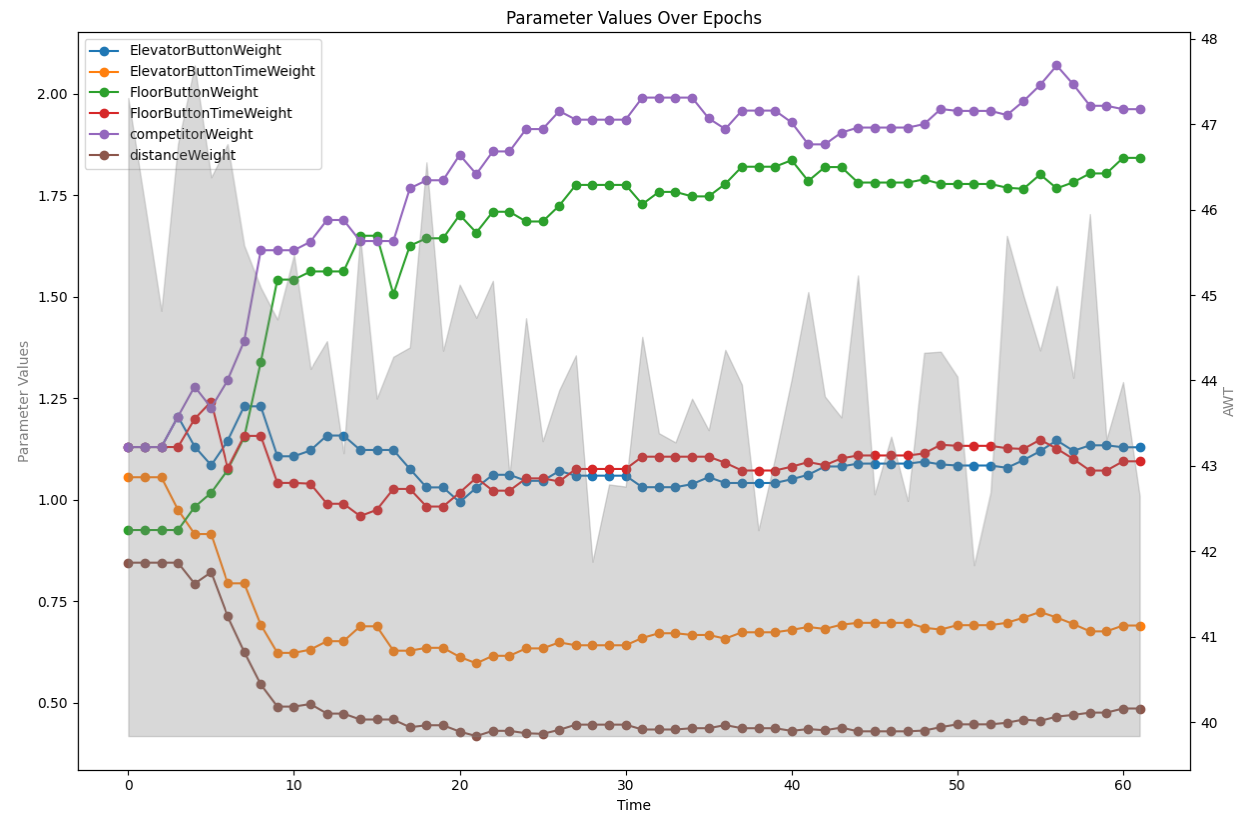


Rooftop Bar Scenario



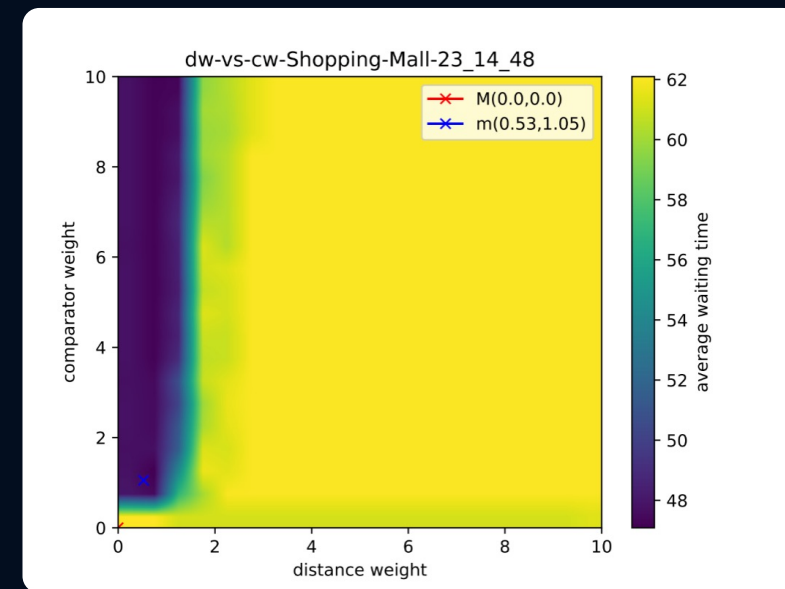
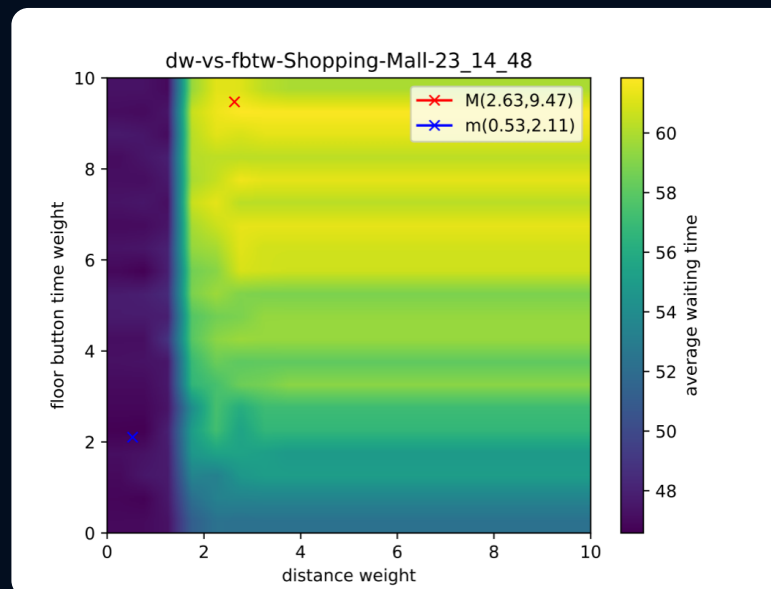
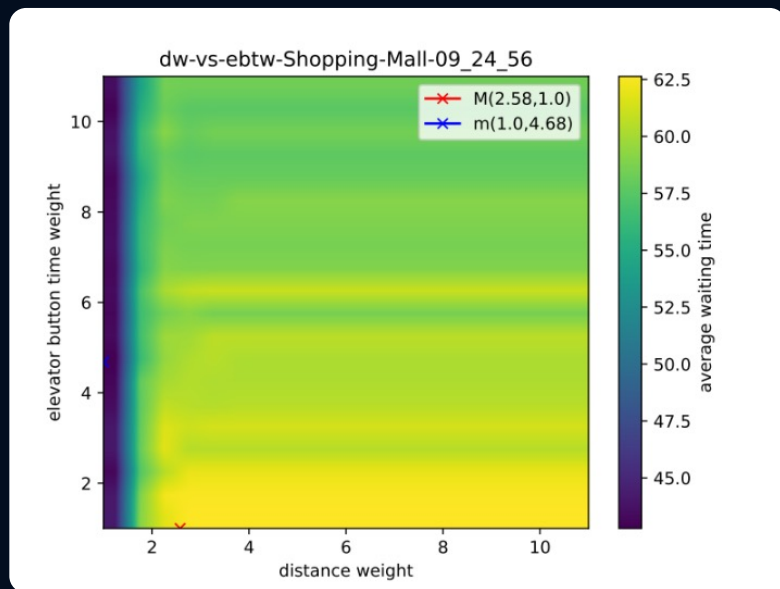
OPTIMIZATION

ITERATIVE PARAMETER MODIFICATION



OPTIMIZATION

DISTANCE WEIGHT DECREASE

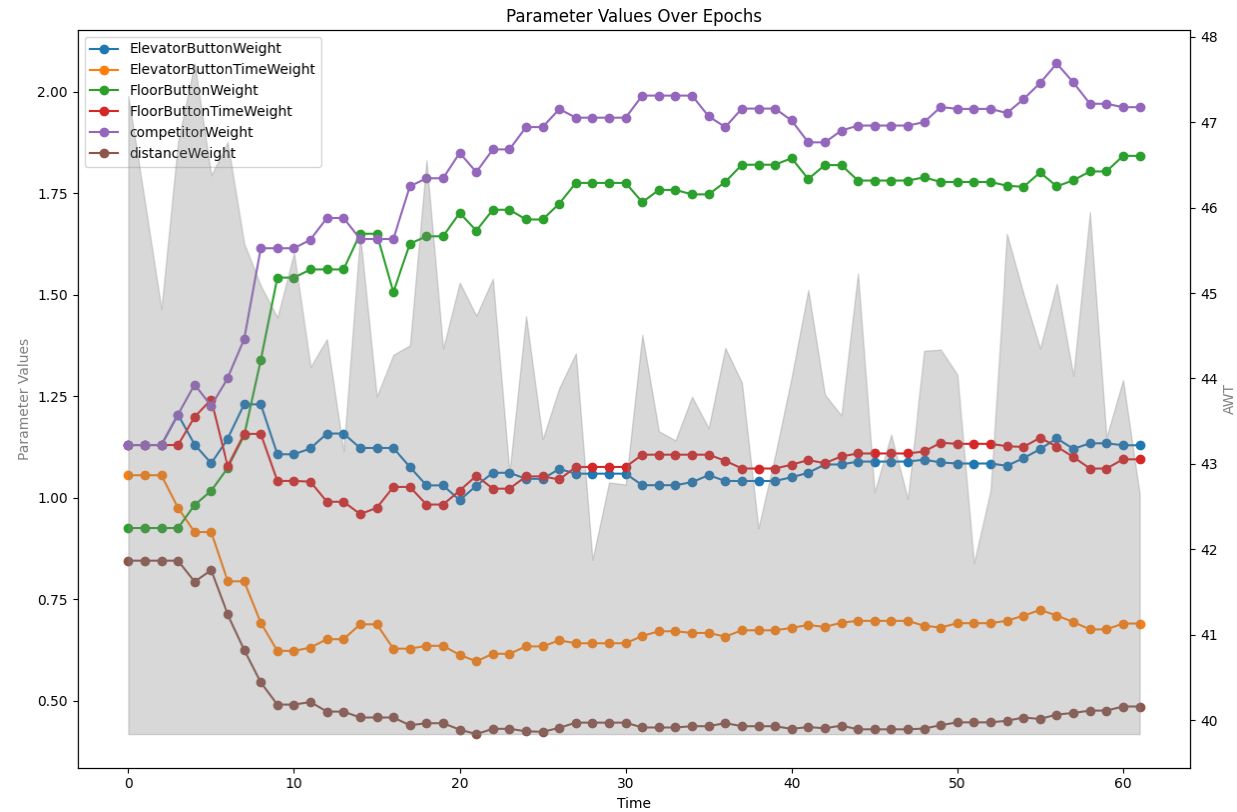


LIVE DEMO

DISTANCE WEIGHT DECREASE

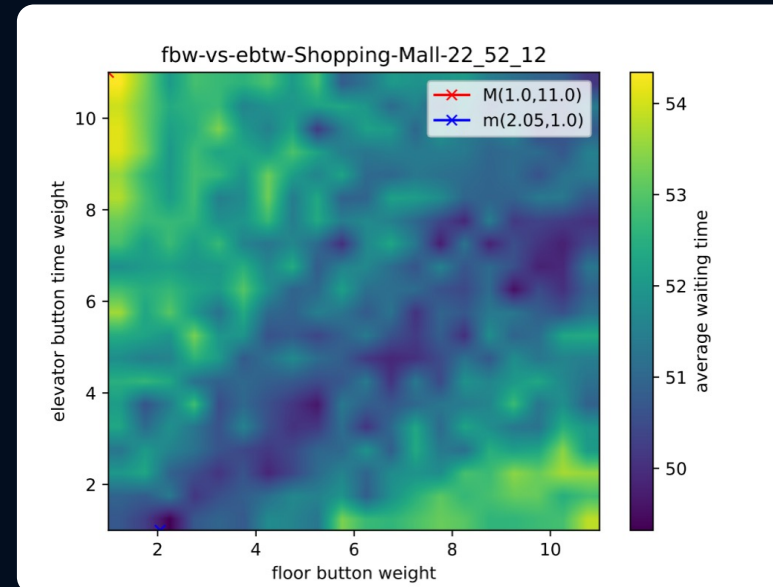
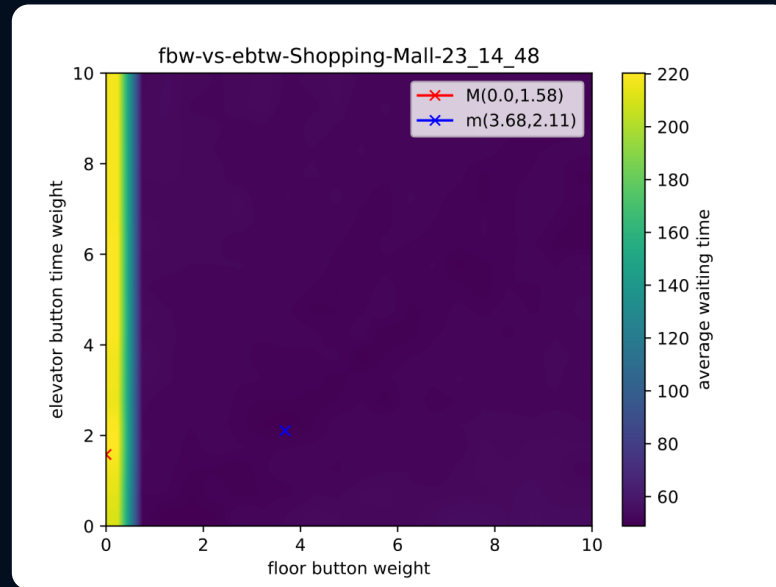
OPTIMIZATION

ITERATIVE PARAMETER MODIFICATION



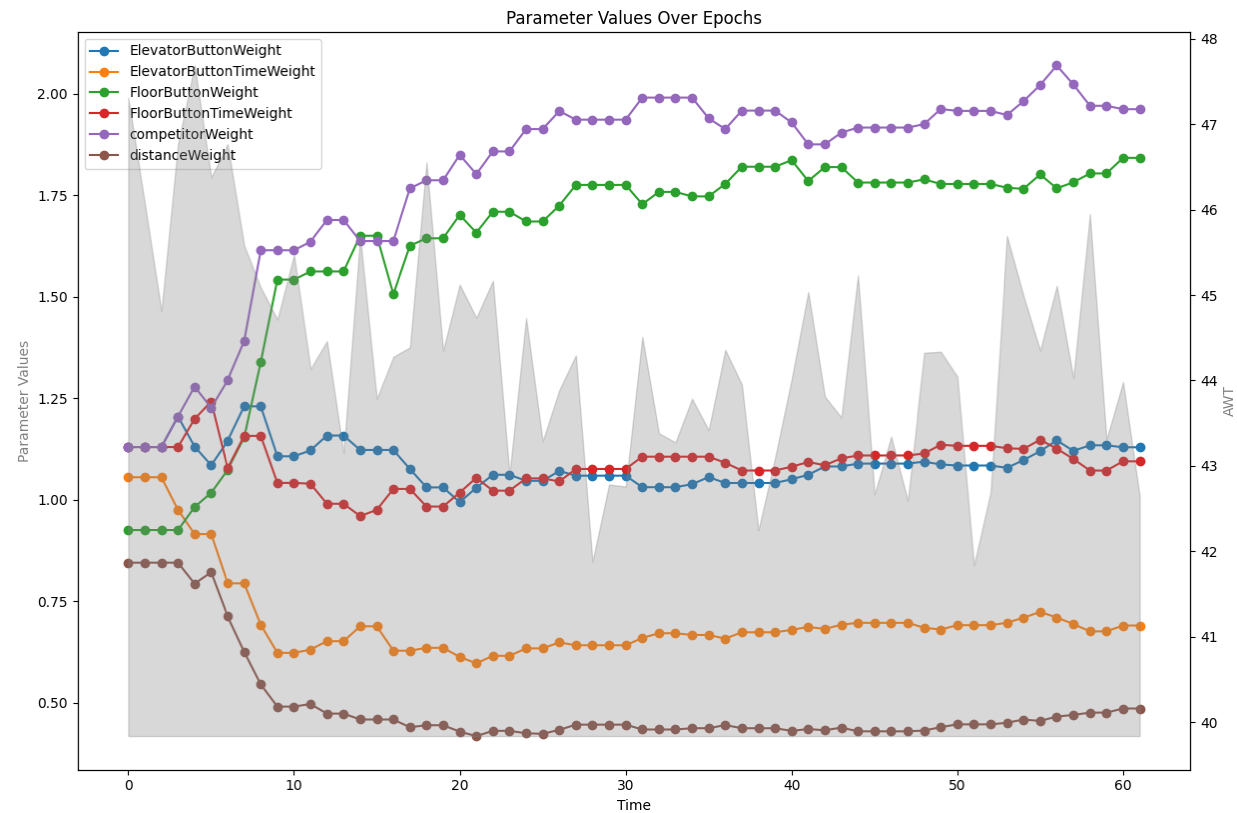
OPTIMIZATION

ELEVATOR TIME WEIGHT DECREASE



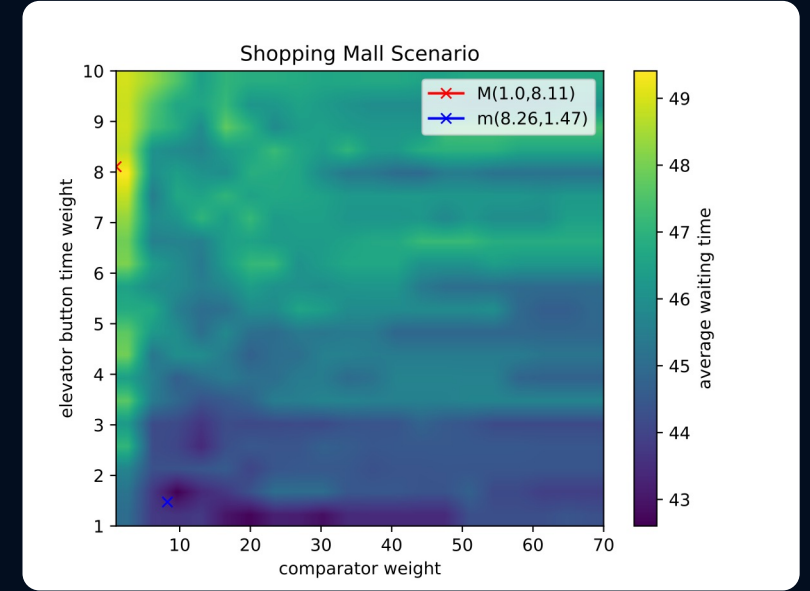
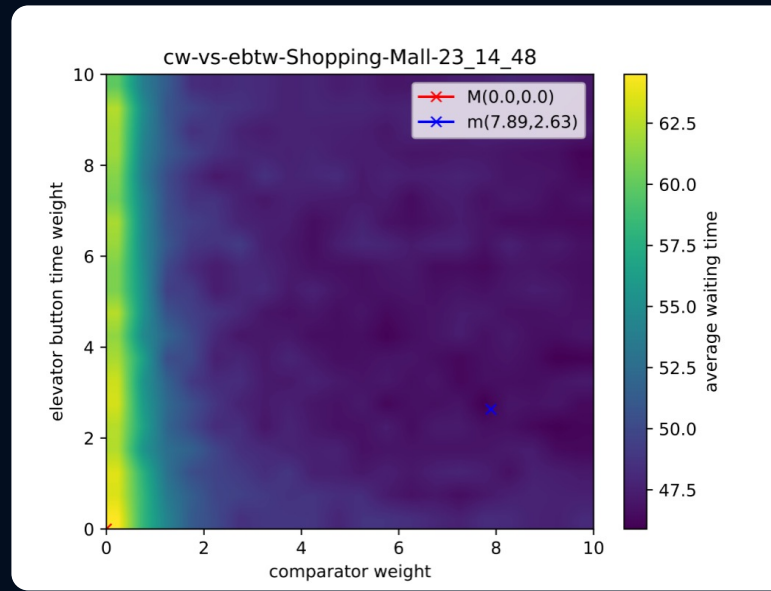
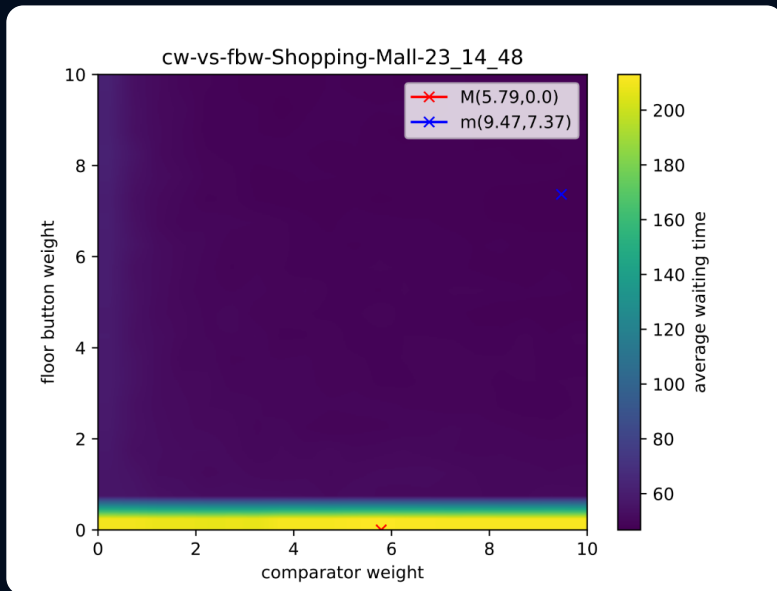
OPTIMIZATION

ITERATIVE PARAMETER MODIFICATION



OPTIMIZATION

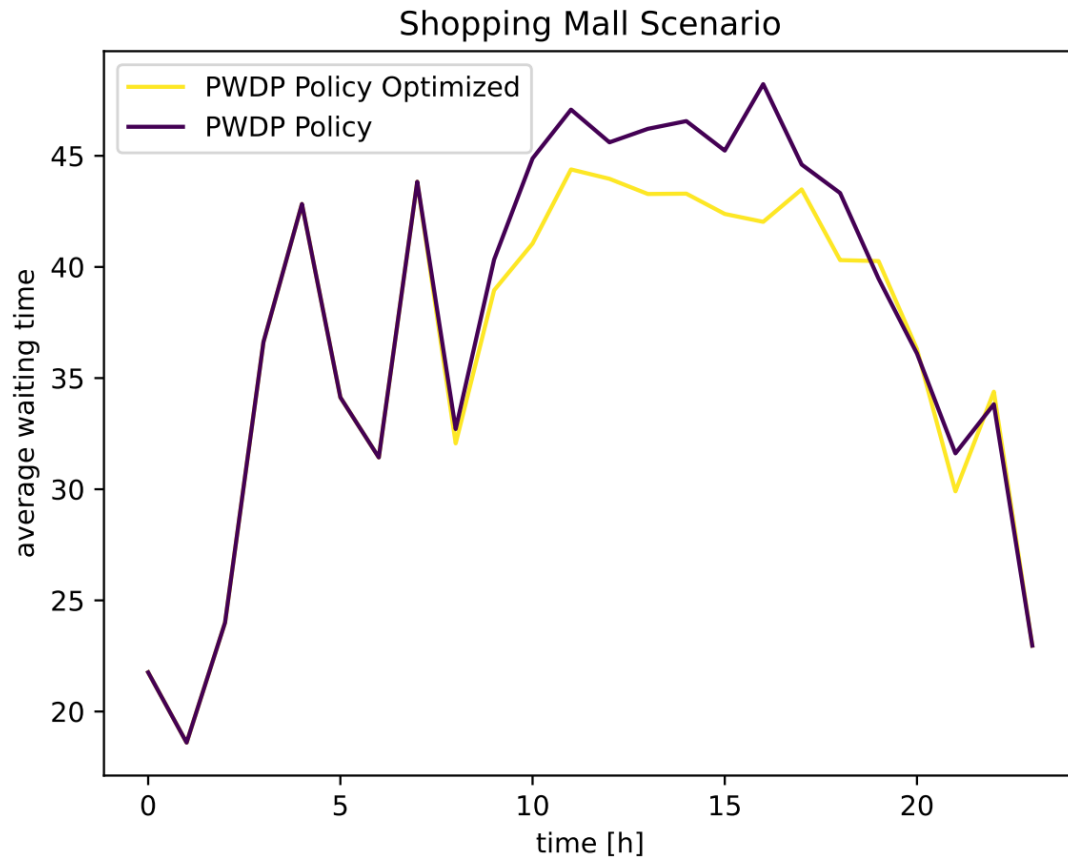
COMPETITOR WEIGHT INCREASE



NORMALIZED OVER BUILDING HEIGHT
→ VALUES GENERALLY LOW

OPTIMIZATION

PERFORMANCE INCREASE



CONCLUSION